



**B.Sc. (Hons.) Year I**

Semester 2 Examination Session

CHE1217: Additional Techniques of Chemical Calculations

20th June 2022

08:30–10:35

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## Instructions

Read the following instructions carefully.

- Attempt only **TWO** questions.
- Each question carries **50** marks. The maximum mark is **100**.
- A list of mathematical formulae is provided on page 2.
- Only the use of non-programmable calculators is allowed.



# MATHEMATICAL FORMULÆ

## ALGEBRA

## CALCULUS

### Factors

$$a^3 + b^3 = (a + b)(a^2 - ab + b^2)$$

$$a^3 - b^3 = (a - b)(a^2 + ab + b^2)$$

### Quadratics

If  $ax^2 + bx + c$  has roots  $\alpha$  and  $\beta$ ,

$$\Delta = b^2 - 4ac$$

$$\alpha + \beta = -\frac{b}{a} \quad \alpha\beta = \frac{c}{a}$$

### Finite Series

$$\sum_{k=1}^n 1 = n \quad \sum_{k=1}^n k = \frac{n(n+1)}{2}$$

$$\sum_{k=1}^n k^2 = \frac{k(k+1)(2k+1)}{6}$$

$$(1+x)^n = \sum_{k=0}^n \binom{n}{k} x^k$$

$$= 1 + nx + \frac{n(n-1)}{2!}x^2 + \dots + x^n$$

## GEOMETRY & TRIGONOMETRY

### Distance Formula

If  $A = (x_1, y_1)$  and  $B = (x_2, y_2)$ ,

$$d(A, B) = \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2}$$

$$= \sqrt{\Delta x^2 + \Delta y^2}$$

### Pythagorean Identity

$$\cos^2 \theta + \sin^2 \theta = 1$$

### General Solutions

$$\cos \theta = \cos \alpha \iff \theta = \pm \alpha + 2\pi\mathbb{Z}$$

$$\sin \theta = \sin \alpha \iff \theta = (-1)^n \alpha + \pi n, \quad n \in \mathbb{Z}$$

$$\tan \theta = \tan \alpha \iff \theta = \alpha + \pi\mathbb{Z}$$

### Derivatives

$f(x)$	$f'(x)$	$f(x)$	$\int f(x) dx$
$x^n$	$nx^{n-1}$	$x^n \ (n \neq -1)$	$\frac{x^{n+1}}{n+1}$
$\sin x$	$\cos x$	$\sin x$	$-\cos x$
$\cos x$	$-\sin x$	$\cos x$	$\sin x$
$\tan x$	$\sec^2 x$	$\tan x$	$\log(\sec x)$
$\cot x$	$-\operatorname{cosec}^2 x$	$\cot x$	$\log(\sin x)$
$\sec x$	$\sec x \tan x$	$\sec x$	$\log(\sec x + \tan x)$
$\operatorname{cosec} x$	$-\operatorname{cosec} x \cot x$	$\operatorname{cosec} x$	$\log(\tan \frac{x}{2})$
$e^x$	$e^x$	$e^x$	$e^x$
$\log x$	$1/x$	$1/x$	$\log x$
$uv$	$u'v + uv'$	$\frac{1}{a^2+x^2}$	$\frac{1}{a} \tan^{-1}(\frac{x}{a})$
$u/v$	$(u'v - uv')/v^2$	$\frac{x}{\sqrt{a^2+x^2}}$	$\sin^{-1}(\frac{x}{a})$

### Integrals

### Homogeneous Linear Second Order ODEs

If the roots of  $ak^2 + bk + c$  are  $k_1$  and  $k_2$ , then the differential equation  $ay'' + by' + cy = 0$  has general solution

$$y(x) = \begin{cases} c_1 e^{k_1 x} + c_2 e^{k_2 x} & \text{if } k_1 \neq k_2 \\ c_1 e^{kx} + c_2 x e^{kx} & \text{if } k = k_1 = k_2 \\ e^{\alpha x} (c_1 \cos \beta x + c_2 \sin \beta x) & \text{if } k = \alpha \pm \beta i \in \mathbb{C} \end{cases}$$

### Infinite Series

$$e^x = \sum_{n=0}^{\infty} \frac{x^n}{n!} = 1 + x + \frac{x^2}{2} + \frac{x^3}{3!} + \frac{x^4}{4!} \dots$$

$$\cos x = \sum_{\substack{n=0 \\ n \text{ even}}}^{\infty} \frac{(-1)^{\frac{n}{2}}}{n!} x^n = 1 - \frac{x^2}{2} + \frac{x^4}{4!} - \dots$$

$$\sin x = \sum_{\substack{n=1 \\ n \text{ odd}}}^{\infty} \frac{(-1)^{\frac{n-1}{2}}}{n!} x^n = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \dots$$

$$\log(1+x) = \sum_{n=1}^{\infty} \frac{(-1)^{n+1}}{n} x^n = x - \frac{x^2}{2} + \frac{x^3}{3} - \dots, \quad x \in (-1, 1]$$

⚠ Attempt only **TWO** questions.

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1. Consider the matrix

$$\mathbf{A} = \begin{pmatrix} -3 & 2 & 2 \\ 2 & 0 & -2 \\ -2 & 1 & a \end{pmatrix}.$$

- (a) Find the inverse matrix  $\mathbf{A}^{-1}$ . State the value(s) of  $a$  for which your answer is valid.
- (b) Consider the system of equations

$$\begin{cases} -3x + 2y + 2z = 1 \\ 2x - 2z = 4 \\ -2x + y + az = b. \end{cases}$$

For what values of  $a$  and  $b$  does this system have:

- (i) a unique solution?
- (ii) infinitely many solutions?
- (iii) no solutions?
- (c) (i) Solve the system in (b) when  $a = b = 1$ .
- (ii) Solve the system in (b) when  $a = \frac{3}{2}$  and  $b = -\frac{1}{2}$ .
- (d) For this part of the question, assume that  $\mathbf{A}$  has  $a = 1$ .
- (i) Find the eigenvalues of  $\mathbf{A}$ .
- (ii) Hence, determine  $\mathbf{P}$  and  $\mathbf{D}$  such that  $\mathbf{A} = \mathbf{PDP}^{-1}$ , where  $\mathbf{D}$  is a diagonal matrix. (You don't need to find  $\mathbf{P}^{-1}$ ).
- (iii) The functions  $x(t)$ ,  $y(t)$  and  $z(t)$ , are related by the differential equations

$$\begin{cases} x'(t) = -3x(t) + 2y(t) + 2z(t) \\ y'(t) = 2x(t) - 2y(t) \\ z'(t) = -2x(t) + y(t) + z(t). \end{cases}$$

Solve for  $x(t)$ ,  $y(t)$  and  $z(t)$ .

[12, 6, 7, 25 marks]

2. (a) The function  $f$  three variables  $x$ ,  $y$  and  $z$  satisfies

$$\frac{\partial f}{\partial x} = 2xz + 3y \quad \text{and} \quad \frac{\partial f}{\partial z} = x^2 - 15y^2z^2.$$

Show that

$$f(x, y, z) = x^2z + 3xy - 5y^2z^3 + c(y),$$

where  $c$  is some function in  $y$  alone.

- (b) (i) Suppose  $f(x, y)$  is separable, i.e., we may write express  $f$  as a product  $f(x, y) = X(x)Y(y)$ . Explain why

$$\frac{\partial f}{\partial x} = \frac{dX}{dx} Y(y) \quad \text{and} \quad \frac{\partial f}{\partial y} = X(x) \frac{dY}{dy}.$$

- (ii) Suppose  $f$  is a function of two variables  $x$  and  $y$ , and that

$$\frac{\partial f}{\partial x} + x^2 \frac{\partial f}{\partial y} = 0.$$

Determine the general solution, assuming it is separable.

- (c) (i) If  $f(x, y)$  is separable, show that

$$\nabla^2 f = \frac{d^2 X}{dx^2} Y(y) + X(x) \frac{d^2 Y}{dy^2}.$$

- (ii) The Schrödinger equation for a particle of mass  $m$  moving in the two-dimensional  $xy$ -plane is

$$-\frac{\hbar^2}{2m} \nabla^2 \Psi = E\Psi,$$

where  $\hbar$  and  $E$  are constants,  $\nabla^2$  is the Laplacian operator, and  $\Psi = \Psi(x, y)$  is the wave function. Assuming the solutions is separable, and that  $X(0) = Y(0) = X(a) = Y(b) = 0$ , show that

$$\Psi(x, y) = C \sin\left(\frac{m\pi}{a}x\right) \sin\left(\frac{n\pi}{b}y\right),$$

where  $C$  is some constant.

**[10, 15, 25 marks]**

3. (a) The Fibonacci numbers  $F_n$  are defined by the recurrence relation

$$\begin{pmatrix} F_{n+1} \\ F_n \end{pmatrix} = \begin{pmatrix} F_n + F_{n-1} \\ F_n \end{pmatrix},$$

where  $\begin{pmatrix} F_1 \\ F_0 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ .

The *golden ratio*  $\varphi$  is the number  $\frac{1}{2}(1 + \sqrt{5})$ .

- (i) Show that

$$1 - \varphi = -\frac{1}{\varphi} = \frac{1}{2}(1 - \sqrt{5}) \quad \text{and} \quad 2\varphi - 1 = \sqrt{5}.$$

- (ii) If  $\mathbf{x}_n = \begin{pmatrix} F_{n+1} \\ F_n \end{pmatrix}$ , show that  $\mathbf{x}_n = \mathbf{A}\mathbf{x}_{n-1}$  for an appropriate  $2 \times 2$  matrix  $\mathbf{A}$ .

- (iii) By diagonalising  $\mathbf{A}$ , solve the recurrence relation and deduce that

$$F_n = \frac{1}{\sqrt{5}} \left( \varphi^n - \left(-\frac{1}{\varphi}\right)^n \right).$$

[Hint: Use  $\varphi$  in your working to keep it simple.]

- (iv) Show that

$$\frac{F_{n+1}}{F_n} = \frac{\varphi - \frac{1}{\varphi^n(-\varphi)^{n+1}}}{1 - \frac{1}{\varphi^n(-\varphi)^n}},$$

and deduce that  $\frac{F_{n+1}}{F_n} \rightarrow \varphi$  as  $n \rightarrow \infty$ .

- (b) Let  $\mathbf{R}$  be the matrix which rotates vectors in 3D by an anticlockwise rotation of  $\theta$  around the  $z$ -axis.

- (i) Find  $\mathbf{R}\mathbf{i}$ ,  $\mathbf{R}\mathbf{j}$  and  $\mathbf{R}\mathbf{k}$ , where  $\mathbf{i}$ ,  $\mathbf{j}$  and  $\mathbf{k}$  are the unit vectors in the  $x$ -,  $y$ - and  $z$ -directions respectively.

- (ii) Hence, show that

$$\mathbf{R} = \begin{pmatrix} \cos\theta & -\sin\theta & 0 \\ \sin\theta & \cos\theta & 0 \\ 0 & 0 & 1 \end{pmatrix}.$$

- (iii) Show that  $\det(\mathbf{R}) = 1$ . What does this mean, geometrically?

[35, 15 marks]

## Solutions

1. (a)  $\mathbf{A}^{-1} = \frac{1}{2(2a-3)} \begin{pmatrix} -2 & 2a-2 & 4 \\ 2a-4 & 3a-4 & 2 \\ -2 & 1 & 4 \end{pmatrix}$ , valid for when  $a \neq \frac{3}{2}$ .

(b) The system is just  $\mathbf{Ax} = \mathbf{b}$ , where  $\mathbf{x} = (x, y, z)$  and  $\mathbf{b} = (1, 4, b)$ .

(i) We get a unique solution when  $\mathbf{A}$  is invertible, i.e., when  $a \neq \frac{3}{2}$ . In this case,  $b$  can be anything.

(ii) Infinitely many solutions occur when  $\mathbf{A}$  is not invertible, i.e., when  $a = \frac{3}{2}$ . Doing Gaussian elimination on the augmented matrix  $(\mathbf{A} \mid \mathbf{b})$  with  $a = \frac{3}{2}$ , one possible sequence of steps gives

$$\left( \begin{array}{ccc|c} -3 & 2 & 2 & 1 \\ 2 & 0 & -2 & 4 \\ -2 & 1 & \frac{3}{2} & b \end{array} \right) \xrightarrow[\begin{array}{l} R_2 + \frac{2}{3}R_1 \rightarrow R_2 \\ R_3 + (-\frac{2}{3})R_1 \rightarrow R_3 \\ R_3 + \frac{1}{4}R_2 \rightarrow R_3 \end{array}]{R_2 + \frac{2}{3}R_1 \rightarrow R_2} \left( \begin{array}{ccc|c} -3 & 2 & 2 & 1 \\ 0 & \frac{4}{3} & -\frac{2}{3} & \frac{14}{3} \\ 0 & 0 & 0 & b + \frac{1}{2} \end{array} \right)$$

The last row corresponds to the equation  $0x + 0y + 0z = b + \frac{1}{2}$ , which has solutions when  $b = -\frac{1}{2}$ . Thus, for infinitely many solutions, we need  $a = \frac{3}{2}$  and  $b = -\frac{1}{2}$ .

(iii) From the previous part, we see that if  $a = \frac{3}{2}$  but  $b \neq -\frac{1}{2}$ , then the system is inconsistent, and we get no solutions.

(c) (i) When  $a = b = 1$ , the matrix  $\mathbf{A}$  is invertible, so the solution is just  $\mathbf{x} = \mathbf{A}^{-1}\mathbf{b} = (-1, 2, -3)$ , i.e.,  $x = -1$ ,  $y = 2$ , and  $z = -3$ .

(ii) This is the case of infinitely many solutions. With reference to part (b)(ii), we have two restrictions on the three variables  $x$ ,  $y$  and  $z$ . Letting  $z = \lambda \in \mathbb{R}$ , then  $R_2$  gives

$$\frac{4}{3}y - \frac{2}{3}\lambda = \frac{14}{3} \implies y = \frac{7+\lambda}{2},$$

and then  $R_1$  gives

$$-3x + 2\left(\frac{7+\lambda}{2}\right) + 2\lambda = 1 \implies x = \frac{6+\lambda}{3}.$$

Therefore, the system has the general solution  $x = \frac{1}{3}(6 + \lambda)$ ,  $y = \frac{1}{2}(7 + \lambda)$ , and  $z = \lambda$  for any  $\lambda \in \mathbb{R}$ .

(d) (i) We have the characteristic polynomial

$$\chi_{\mathbf{A}}(\lambda) = \det(\lambda \mathbf{I} - \mathbf{A}) = \lambda^3 + 2\lambda^2 - 2\lambda - 2 = (\lambda - 1)(\lambda + 1)(\lambda + 2),$$

so the eigenvalues are  $\lambda = \pm 1, -2$ .

(ii) We determine corresponding eigenvectors for each eigenvalue:

For  $\lambda = 1$ ,  $\mathbf{x} = (1, 2, 0)$ ,

For  $\lambda = -1$ ,  $\mathbf{x} = (1, 0, 1)$ ,

For  $\lambda = -2$ ,  $\mathbf{x} = (4, -1, 3)$ .

Thus if we define  $\mathbf{P} = \begin{pmatrix} 1 & 1 & 4 \\ 2 & 0 & -1 \\ 0 & 1 & 3 \end{pmatrix}$ , we get

$$\mathbf{A} = \mathbf{P} \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -2 \end{pmatrix} \mathbf{P}^{-1}.$$

(iii) The given differential equations are equivalent to the matrix equation  $\dot{\mathbf{x}} = \mathbf{A}\mathbf{x}$ , where  $\mathbf{x} = \mathbf{x}(t) = (x(t), y(t), z(t))$ .

Using the diagonalised form, this is  $\dot{\mathbf{x}} = \mathbf{P}\mathbf{D}\mathbf{P}^{-1}\mathbf{x}$ , equivalently,  $\mathbf{P}^{-1}\dot{\mathbf{x}} = \mathbf{D}\mathbf{P}^{-1}\mathbf{x}$ . If we let  $\mathbf{u} = \mathbf{P}^{-1}\mathbf{x}$ , then this is  $\dot{\mathbf{u}} = \mathbf{D}\mathbf{u}$ , i.e.,

$$\begin{pmatrix} x'(t) \\ y'(t) \\ z'(t) \end{pmatrix} = \begin{pmatrix} x(t) \\ -y(t) \\ -2z(t) \end{pmatrix}.$$

In general, the differential equation  $f'(t) = af(t)$  is equivalent to  $\frac{f'(t)}{f(t)} = a$ , and integrating both sides with respect to  $t$ , we get  $\log(f(t)) = at + \log c$ , i.e.,  $f(t) = ce^{at}$ . So the vector differential equation above becomes

$$\begin{pmatrix} x(t) \\ y(t) \\ z(t) \end{pmatrix} = \begin{pmatrix} Ae^t \\ Be^{-t} \\ Ce^{-2t} \end{pmatrix},$$

and thus we've determined the solution  $\mathbf{u}(t)$  of  $\mathbf{\Omega} = \mathbf{D}\mathbf{u}$ . Now to translate this into the desired solution  $\mathbf{x}(t)$  of the original equation, we use the fact that  $\mathbf{x} = \mathbf{P}\mathbf{u}$ :

$$\mathbf{x}(t) = \mathbf{P}\mathbf{u}(t) = \begin{pmatrix} Ae^t + Be^{-t} + 4Ce^{-2t} \\ 2Ae^t - Ce^{-2t} \\ Be^{-t} + 3Ce^{-2t} \end{pmatrix},$$

i.e., the solution is

$$\begin{cases} x(t) = Ae^t + Be^{-t} + 4Ce^{-2t} \\ y(t) = 2Ae^t - Ce^{-2t} \\ z(t) = Be^{-t} + 3Ce^{-2t}. \end{cases}$$

2. (a) Integrating both derivatives gives the result.  
 (b) (i) By the product rule,

$$\begin{aligned} \frac{\partial f}{\partial x} &= \frac{\partial}{\partial x}(X(x)Y(y)) \\ &= \frac{\partial X}{\partial x} Y(y) + X(x) \frac{\partial Y}{\partial y} = \frac{dX}{dx} Y(y), \end{aligned}$$

and similarly for  $\frac{\partial f}{\partial y}$ .

- (ii) Assuming  $f = XY$ , differential equation is

$$\frac{dX}{dx} Y + x^2 X \frac{dY}{dy} = 0,$$

which rearranges into

$$\frac{1}{x^2 X} \frac{dX}{dx} + \frac{1}{Y} \frac{dY}{dy} = 0,$$

and so we must have

$$\frac{1}{x^2 X} \frac{dX}{dx} = C \quad \text{and} \quad \frac{1}{Y} \frac{dY}{dy} = -C$$

for some constant  $C$ .



These are separable first order ODEs, which have solutions  $X = Ae^{Cx^3/3}$  and  $Y = Be^{-Cy}$  respectively. Thus we obtain the general solution  $f = XY = ABe^{C(x^3/3-y)}$ , or, if we relabel the constants,

$$f(x,y) = Ae^{C(\frac{x^3}{3}-y)}.$$

- (c) (i) Similar to (b)(i), using the product rule twice.  
(ii) By part (i), assuming  $\Psi = XY$ , the equation is just

$$\frac{d^2X}{dx^2}Y + X\frac{d^2Y}{dy^2} = -\frac{2mE}{\hbar^2}\Psi,$$

and dividing through by  $\Psi = XY$ , we get

$$\frac{1}{X}\frac{d^2X}{dx^2} + \frac{1}{Y}\frac{d^2Y}{dy^2} = -\frac{2mE}{\hbar^2}.$$

Thus we have

$$\frac{1}{X}\frac{d^2X}{dx^2} = -C_1 \quad \text{and} \quad \frac{1}{Y}\frac{d^2Y}{dy^2} = -C_2$$

where  $C_1 + C_2 = 2mE/\hbar^2$ . In other words,

$$X'' + C_1X = 0 \quad \text{and} \quad Y'' + C_2Y = 0.$$

These are second order differential equations with constant coefficients, and they have solutions

$$X = A\sin(\sqrt{C_1}x) \quad \text{and} \quad Y = B\sin(\sqrt{C_2}y)$$

respectively (notice the boundary conditions  $X(0) = Y(0) = 0$  give the forms above).

Moreover, since  $X(a) = 0$ , we have  $\sin(\sqrt{C_1}a) = 0$ , so we must have  $\sqrt{C_1}a = m\pi$  for some  $m$ , i.e.,  $\sqrt{C_1} = m\pi/a$ . Similarly, since  $Y(b) = 0$ , we get that  $\sqrt{C_2} = n\pi/b$  for some integer  $n$ .

Thus, relabelling  $AB$  with  $C$ , we get

$$\Psi = XY = C\sin\left(\frac{m\pi}{a}x\right)\sin\left(\frac{n\pi}{b}y\right).$$

3. (a) (i) Simple algebra.

(ii) We have

$$\mathbf{x}_n = \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} \mathbf{x}_{n-1}.$$

(iii) The diagonalisation is

$$\mathbf{A} = \frac{1}{\sqrt{5}} \begin{pmatrix} \varphi & 1-\varphi \\ 1 & 1 \end{pmatrix} \begin{pmatrix} \varphi & 0 \\ 0 & 1-\varphi \end{pmatrix} \begin{pmatrix} 1 & \varphi-1 \\ -1 & \varphi \end{pmatrix},$$

and since  $\mathbf{x}_n = \mathbf{A}^n \mathbf{x}_0$ , where  $\mathbf{x}_0 = \begin{pmatrix} F_1 \\ F_0 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ , we get

$$\begin{aligned} \mathbf{x}_n &= \frac{1}{\sqrt{5}} \begin{pmatrix} \varphi & 1-\varphi \\ 1 & 1 \end{pmatrix} \begin{pmatrix} \varphi^n & 0 \\ 0 & (1-\varphi)^n \end{pmatrix} \begin{pmatrix} 1 & \varphi-1 \\ -1 & \varphi \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} \\ \Rightarrow \begin{pmatrix} F_{n+1} \\ F_n \end{pmatrix} &= \frac{1}{\sqrt{5}} \begin{pmatrix} \varphi^{n+1} - (1-\varphi)^{n+1} \\ \varphi^n - (1-\varphi)^n \end{pmatrix}, \end{aligned}$$

and comparing the bottom entries gives the required formula.

(iv) This part is just a matter of simplifying the expression  $F_{n+1}/F_n$  using the formula. When  $n \rightarrow \infty$ , the terms in  $n$  go to zero, and we get that  $F_{n+1}/F_n \rightarrow \varphi/1 = \varphi$ .

(b) (i) For this question, a quick sketch or verbal argument suffices to obtain these coordinates.

$$\mathbf{Ri} = (\cos \theta, \sin \theta, 0)$$

$$\mathbf{Rj} = (-\sin \theta, \cos \theta, 0)$$

$$\mathbf{Rk} = (0, 0, 1).$$

(ii) The matrix is just the images of  $\mathbf{i}, \mathbf{j}, \mathbf{k}$  in its columns.

(iii) The proof involves the Pythagorean identity for simplification. It means that the volume of any regions which we apply  $R$  to remains unchanged (it will be multiplied by 1).